



**Course Title: FLIGHT DYNAMICS**

**Credit Units: 03**

**Course Code: AERO408**

**Course Level: UG**

L	T	P/S	SW/ FW	TOTAL CREDIT UNITS
2	1	-	-	3

### Course Objectives

This course is designed to make the students understand the complexities of airplane & rocket dynamics. Six degree of freedom analysis of Flight vehicles, along with stability and control aspects. A comprehensive analysis of aircraft motion and stability will be stressed upon in this course.

**Pre-requisites:** Aircraft stability & control, Airplane Performance.

### Course Contents/Syllabus:

	Weightage (%)
<b>Module I : Introduction</b>	<b>15</b>
<b>Descriptors/Topics:</b> Fundamentals of vector. Particle and Rigid body kinematics: Fixed frame of reference, rotating frame of reference. Choice of Axes: principal axes, stability axes, body axes. Transformation of coordinates.	
<b>Module II : Aircraft Equations of Motion</b>	<b>25</b>
<b>Descriptors/Topics :</b> General equations of unsteady motion of airplane: Force equations in moving frame, Moment equations in moving frame. Orientation and position of the airplane: Principle Rotation, Euler angles, Euler rates, Transformation matrix. External forces. Angular velocities equations in moving frame. Velocities equations in moving frame. Flight simulation of powered and unpowered flights.	
<b>Module III : Small-Disturbance Theory</b>	<b>25</b>
<b>Descriptors/Topics :</b> Linearized equations of aircraft motion: Control fixed longitudinal equations, control fixed lateral-directional equations. Stability criteria. Stability analysis of linearized equations of motion. Airplane longitudinal motion: Short period approximation, Phugoid approximation. Airplane lateral motion: Spiral approximation, Roll approximation, Dutch roll approximation. Sample calculation on longitudinal and lateral motion approximations.	

<b>Module IV : Stability Derivatives</b>	<b>20</b>
<b>Descriptors/Topics :</b> Expressions for $C_x$ , and $C_z$ . The $\alpha$ Derivatives: $Cx_\alpha, Cz_\alpha, Cm_\alpha$ . The $u$ Derivatives: $Cx_u, Cz_u, Cm_u$ . The $q$ Derivatives: $Cz_q, Cm_q$ . The $\dot{\alpha}$ Derivatives: $C_{L\dot{\alpha}}, C_{m\dot{\alpha}}$ . The $\beta$ Derivatives: $C_{y\beta}, C_{l\beta}, C_{n\beta}$ . The $p$ Derivatives: $C_{yp}, C_{lp}, C_{np}$ . The $r$ Derivatives: $C_{yr}, C_{lr}, C_{nr}$ .	
<b>Module V : Fundamentals of Rocket Dynamics</b>	<b>15</b>
<b>Descriptors/Topics :</b> Classification of rockets. Flight performance of single stage rocket. Design parameters. Performance in terms of design parameters. Flight performance of multi-stage rocket.	

### Student Learning Outcomes:

- Develop 6DOF mathematical model to predict dynamic response of the flight vehicles.
- Define stability criterion of the flight vehicles.
- Differentiate and examine different modes of the aircraft motion.
- Evaluate and predict dynamic response of the flight vehicles corresponding to various control inputs
- Calculate performance of single and multi-stage rockets.

**Pedagogy for Course Delivery:** Session Plan / course-material uploading, Class-room teaching associated with assignments, presentations, quiz, viva-voce and evaluation.

### Assessment/ Examination Scheme:

Theory L/T (%)	Lab/Practical/Studio (%)	Total
100	NA	70

**Theory Assessment (L&T):**

<b>Continuous Assessment/Internal Assessment - 30</b>					<b>End Term Examination</b>
<b>Components (Drop down)</b>	<b>A</b>	<b>CT</b>	<b>S/V/Q</b>	<b>HA</b>	<b>70</b>
<b>Weightage (%)</b>	5	10	8	7	70

**Text & References:**

- Etkin, B., “*Dynamics of Flight*” 3<sup>rd</sup> Edition, John Wiley & Sons, INC.
- Meriam, J. L., “*Dynamics*” John Wiley & Sons, INC.
- Nelson, R. C., “*Flight Stability and Automatic Control*”, McGraw-Hill
- Roy, A. E., “*Foundation of Astrodynamics*”, Macmillan.
- Kaplan, M. H., “*Spacecraft Dynamics and Control*”, John Wiley & Sons, INC.

**Any other Study Material:**

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